Smart Ambulances for IoT Based Accident Detection, Tracking and Response

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Abstract: One of the main reasons for death among young people in the current era is based on road accidents. The goal of current research on accident detection systems is to shorten reporting times, increase accident detection accuracy and address them through our modern technology. Our primary goal is to recommend a system that can successfully aid in preventing any kind of accident and if such conditions exist, then how it detects and alerts the relevant authorities and people so that the problem can be handled and addressed swiftly. Automatic mechanisms for detecting traffic accidents must be put in place if assistance is to be given right away. The proposed system model Emergency Request Response and Management System (ERMS) takes the benefit of Vibration sensors (VC) and Accelerometers (AB) through the proposed phases namely AcciDet TracSys and AcciAddr TracSys. Wherein, the AcciDet TracSys helps in detection of the accident, explained in detail in this study and AcciAddr TracSys helps address the people met with an accident through technical ways that are explained in detail in this study, also tracing the location of smart ambulances. With the help of the global positioning system, the accident location is sent to the smart ambulance for timely arrival and is also tracked for further assistance through the internet. Finally, this information is communicated to the main contacts of the accident victim, so that they can reach the hospital on time. Our proposed work meets the need to assist the injured after an accident through the accident detection and addressing system, as just only notifying neighboring ambulances does not cater to the solution to the problem.

Keywords: GSM, GPS, Accident Detection, IoT, Accelerometer, Smart Car, Smart Ambulance

Introduction

According to the WHO's global status report, which includes data from around 180 countries, the number of people worldwide who die in traffic accidents has risen to 1.25 million per year, with low-income nations having the highest rates. The demand for vehicles has grown significantly as a result of the world population's rapid growth and thus, issues with traffic congestion and road accidents have also become worse. Because the lives of the general public are in danger and accidents result in slow reactions that increase the number of fatalities, an automatic accident detection system is necessary to address this issue. A collision involving any on-road vehicle, an obstruction, or a pedestrian might be viewed as a road crash. The amount of time it takes for an ambulance to get to the accident scene and then transport the patient to the hospital has a significant impact on the victim's chance of survival. Singh et al. (2021) intends to speed up the emergency response department's ability to learn about car accidents in Malaysia. The majority of times when a person is injured in a car accident, the damage is not serious and the sufferer can be saved; nevertheless, if the rescue teams are late, the damage becomes fatal. For the rescue teams to be able to act quickly to save the victim's life, the first objective is to locate the accident's location and convey that information to them as soon as possible. Internet of Things (IoT) based Advanced Transport Systems (ATS) are becoming more and more well-liked and are viewed as a potential option to increase traffic safety. Reducing the time, it takes to respond to an accident is one practical way to lessen traffic hazards and save priceless lives. To address this issue and reduce the response time following an accident, much study has been conducted. We suggest an internet-based Emergency Request Response and Management System (ERMS) to address the aforementioned issues as the main goal of the suggested system. Additionally discussed is the system's architecture.
Using the built-in sensors that collect the necessary data for detecting an accident lowers the overall system cost. Telegram is a smartphone application that is utilized. GPS technology is used to obtain the location data. The collected data is forwarded to the closest nodes for any additional processing that may be required. If an accident is found, the position of an ambulance is discovered and addressed immediately to provide aid to the victims. The flow of ERMS's system is discussed in Fig. 1.

The time it takes to respond to a disaster, whether it be natural or man-made, is one of the most crucial elements in lowering the number of fatalities. Given the seriousness of the problem, extensive research has been done to find a solution, leading to improvements in emergency anticipatory systems. Fog-based disaster management systems, cloud-based accident detection and disaster management systems, and smartphone-based disaster management systems are some new research topics in this area. Another research proposes a system to automatically turn on green traffic signals in an ambulance's path using an RF module. For the ambulance to timely arrive at the spot (Saxene, 2014). Given that the service is centralized, cloud-based accident detection and disaster management systems may encounter problems with latency and bandwidth (Tian et al., 2019). Smartphone-based accident detection can relieve general traffic and improve emergency personnel readiness (Thompson et al., 2010). Fog computing, which promises to have lower latency, enhance mobility, increase resilience, and be scalable, is a new idea that can help with these problems (Dar et al., 2019). Dhivyaa et al. (2018) proposes an IoT based ambulance traffic light signal controlling system. In addition, crash detection and management systems can be made accessible also simple to install in older automobiles by leveraging smartphone sensors (Thompson et al., 2010). In this study (Razali et al., 2021), the authors propose an Accident Detection and Classification (ADC) system for smartphones that, in addition to detecting accidents, also categorizes them as collisions. Table 1 describes the developments in research for accident detection and briefs about a suggested solution.

The literature review session helps us to understand the gap between the work that has been done so far by the researchers and our proposed work. Through the above study, we realize that researchers have found various ways of detecting accidents and intimation to the primary contacts through SMS and finding the accident spot through GPS only. But, the system i.e., ERMS proposed in this study accepts the call by the ambulance and acknowledges the primary contacts, and traces the smart ambulance to know the estimated time of the arrival of an ambulance to the spot. A detailed explanation is provided in the proposed methodology.
Table 1: Accident detection through various approaches by other researchers

<table>
<thead>
<tr>
<th>Reference. no</th>
<th>Title of article</th>
<th>Year of publication</th>
<th>Observation/findings</th>
</tr>
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<tbody>
<tr>
<td>Dut et al. (2019)</td>
<td>Delay aware accident detection and response system using fog computing</td>
<td>2019</td>
<td>The development of an Android application makes use of the incident detection capabilities of smartphone sensors. A course of action is developed when an accident is discovered. Initially, the Global Positioning System is used to find a nearby hospital (GPS). Following notification of the accident to the hospital's emergency department, an ambulance is dispatched to the scene. Based on specific factors and processes connected to the automotive architecture of the vehicle, the crash sensors will quantify and report the collision's severity. The IoT sensors that are close by and can assist the victims will then be informed by the collision's strength as it is scaled.</td>
</tr>
<tr>
<td>Singhal and Tomar's (2016)</td>
<td>Intelligent accident management system uses IoT and cloud compute</td>
<td>2016</td>
<td>This study explores the viability of fitting a car with equipment that can instantly notify emergency services of an accident and identify it. Whenever a crash occurs, someone must actively seek assistance, such as by dialing 911 for emergency services. Friends, relatives, the police, or an ambulance are automatically notified.</td>
</tr>
<tr>
<td>Shaik et al. (2018)</td>
<td>Smart car: An IoT based accident detection system</td>
<td>2018</td>
<td>Their technology by them offers a unique prevention and system that disperses the ultimate cure for drivers, ensuring safety and preventing loss of life by taking the proper actions at the correct moment. Additionally, it checks to see whether the driver is drowsy or unstable, which might result in pedal confusion, unintentional acceleration, or incorrect steering.</td>
</tr>
<tr>
<td>Nanda et al. (2018)</td>
<td>An IoT-based smart system for accident prevention and detection</td>
<td>2018</td>
<td>Explains how a collision force is comparable to running into a brick wall at a 10-15 mph pace would look, can be used to trigger a sensor to inflate the bag, thereby facilitating the detection of accident.</td>
</tr>
<tr>
<td>Chaudhary et al. (2021)</td>
<td>Vehicle accident system (using GPS tracker and airbag ECU)</td>
<td>2021</td>
<td>Since dashboard cameras and video surveillance systems are devices that employ vision-based technologies, developed a video-based method to identify car accidents. With limitations on traffic surveillance cameras, a method based on the video from the dashboard, cameras would produce a solution independent of the position of the car.</td>
</tr>
<tr>
<td>Ijjina and Sharma (2019)</td>
<td>Accident Detection from dashboard camera video</td>
<td>2019</td>
<td>This study suggests a fully automated, internet of things based accident detection system. The data is transferred to the web server, instant SMS is sent to the victim's friends and the information is also sent to the appropriate authorities as soon as an incident occurs. A simulated road scenario has been created to assess the system's performance. The outcome of extensive system integration and testing show that the suggested system not only satisfies the research's stated objective but can also give the desired result in a relatively economical manner.</td>
</tr>
<tr>
<td>Karmokar et al. (2020)</td>
<td>A Novel IoT-based accident detection and rescue system</td>
<td>2020</td>
<td>To preserve road safety and save precious lives, it critically analyze the many available approaches for foreseeing and preventing traffic accidents, stressing their advantages, drawbacks and issues that must be resolved.</td>
</tr>
<tr>
<td>Alvi et al. (2020)</td>
<td>A comprehensive study on IoT based accident detection systems for smart vehicles</td>
<td>2020</td>
<td>This research offers an Internet of Things (IoT) based automotive Accident Detection and Categorization (ADC) system that combines built-in and linked sensors from smartphones to identify the sort of accident and notify it.</td>
</tr>
<tr>
<td>Kumar et al. (2020)</td>
<td>An IoT-based vehicle accident detection and classification system using sensor fusion</td>
<td>2020</td>
<td></td>
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Proposed Methodology

The methodology of the suggested system (ERMS) is described in this section. It is a sensor-based system that makes use of the benefits of gathering data from sensors to discover an accident. The technology eliminates the requirement for an external component and an onboard processing unit, hence decreasing system cost, by using the sensors that are easily available in the marketplace. The servers receive the information obtained by the accelerometer sensor, smoke sensor, tilt sensor, and flame sensor.

A. Architecture of the System

Figure 1, the suggested system is made up of five separate layers. The interface and devices are located at the top layer. Microcontrollers make up the second layer. The database is stored in the following layer and services are the exclusive focus of the fourth layer. The last layer is where the cloud resources are eventually made accessible. The information is gathered and shared with ambulances and primary contacts through Telegram, an Android app.
B. System Implementation

The two main components of the proposed system are crash detection and tracking and emergency response and tracking. A detailed explanation of these systems is discussed in the following sections.

Phase for Detecting Crashes

Identifying the incidence of an accident is the focus of the detection phase. VC, AB, Tilt, and flame sensors with GPS are used for this. Each sensor has thresholds that must be met to assess if an accident has occurred or not. The gravity force (a Grav-force value) is considered through the accelerometer and GPS. If this value is more than 4, an accident can be determined as per previous research. However, utilizing this value alone results in a large percentage of false positives. When measuring an accident, the vehicle's speed is also taken into account. According to previous research, a vehicle is deemed to be in an accident state if its speed period variation is more than 2.06 km/s and uses loss function with dynamic weights and Multi-Scale Feature Fusion (MSFF) to improve the performance of object detection for small objects (Saxene, 2014). The microphone can also be utilized to detect an unusual acoustic event, which increases the reliability of ERMS. The sound threshold is defined as a number greater than 14 dB. A microphone can be employed as a supplementary filter to increase the entire process's reliability.

The detecting phase procedure is described by a flowchart (Fig. 2) and through an algorithm. Before starting the journey, the application is launched by the vehicle's driver. A Unique Individual Identification (U_ID) number is used to identify each vehicle. The application keeps track of the sensor data as it is being acquired. When Grav-force values cross the threshold, an alarm is created for 10 sec and an accident is assumed to have happened unless it's manually switched off through the push button. False alarm information is recorded and kept in the database if the notification is canceled. The alert phase begins if the alert is not canceled.

Implementation of AcciDet_TracSys and flowchart for accident detection and Notification:

1. Start
2. Enable all the sensors
3. Initialize all the module connections with the controller
4. If the values recorded by the accelerometer are above the threshold and if tilt is also recorded, the accident has occurred and is detected
5. The current location of the accident is sent to the microcontroller unit through GPS
6. Buzzer is activated and waits for 10 sec
7. If the driver manually turns off the buzzer, then the buzzer goes back to the initial stage of detecting an accident by monitoring the accelerometer and tilt sensors
8. If else buzzer isn't turned off, then the accident has occurred and is confirmed
9. The camera turns on and captures the image inside the car and the location of the accident is shared with primary contacts and the nearest ambulance through telegram and a message through the GSM module
10. End

Fig. 2: Accident detection and notification
Phase for Addressing the Emergency Response and Tracking

Addressing the emergency response and notification is described by the flowchart (Fig. 3) and a range of sensors, including tilt, AC, and VB sensors, can be utilized to spot accidents. It is possible to program these sensors to read readings that are outside of the allowed range or values that indicate an accident has happened. The vehicle's chassis angle is measured by the tilt sensor, which assesses whether it is at a safe angle. To quantify vibration, shock, and tilt, an accelerometer is used (inclination). Any significant vibrations within the car are picked up by the vibration sensor. Finally, a gyroscope is a tool that uses gravity on Earth to help identify the orientation. The tilt detection of the tilt sensor is also used in this study and can help in finding the safest angle by keeping track of the vehicle's chassis angle. A notification can be sent by SMS, or Telegram after an accident has been detected. Whether Wi-Fi or GSM was utilized as the module will determine the answer. The information is shared only with one particular contact, as was the case with the prior study's Telegram notification proposal (Karmokar et al., 2020). As a result of this study, a telegram group will get the message. If there is a struggle with Wi-Fi coverage issues, this study also utilizes GSM modules and notifications can also be sent via SMS.

Implementation of AcciAddr_TracSys and flowchart for Addressing the emergency response:

1. Start
2. The ambulance receives the intimation of an accident with an image (the image helps analyze the number of people injured inside the car)
3. The ambulance accepts the call and shares its location with primary contacts and owners for tracking online
4. The ambulance reaches the accident location

Materials, Methods and Implementation

Emergency Request Response and Management System (ERMS) with Telegram and SMS notifications are the focus of this study design and development work. As soon as the accident is discovered, it will be started. The tilt-related sensor sends a signal to the MCU activating it. A push button is turned off if there's a false alarm. The GPS module, however, receives latitude and longitude readings from the GPS via MCU. In case, the push button isn't turned off within the allotted (10 sec) period, the location of the accident and notification are communicated through a telegram to the concerned people. The system will use SMS to convey the notification and accident location if there is no 3-4G service. This system has the benefit that the notification can be sent by GSM and also through Wi-Fi.

Implementation of the system encompasses two stages:

1. Hardware, software, and integration
2. Evaluating the model

![Fig. 3: Accident addressing the emergency response and notification](image-url)
Hardware, Software and Integration

Figure 4 explains the integration of all the above components discussed in Table 2 which helps to detect the accident and provide emergency requests and responses via IoT.

Softerwares used in the accident detection ERMS are: The data are being sent to a server which further sends to a provided phone using telegram.

Raspberry Pi programming: The Raspberry Pi-OS is primarily used by the Raspberry Pi device and in this section, we describe the programming language that is used by the Raspberry Pi. Raspberry Pi-OS, primarily employs the Python programming language to carry out various tasks.

Python programming has many features to add to developing different types of AI/Internet of Things-related projects. Built-in python IDE of Raspberry Pi enables the building and execution of various Python-based programs. It also supports other languages such as C, C++, Fortran, Java, and many others.

SQLite programming: The relational database management system SQLite is independent of the usual client-server architecture. The fact that this database system is integrated right into the software sets it apart from MySQL and MariaDB. It can run independently of a server. SQLite stores its SQL information in a file that is present alongside your software rather than relying on an external system.
Table 3: Predicting the severity of accident through Grav-forces

<table>
<thead>
<tr>
<th>Network</th>
<th>Grav_force</th>
<th>Severity of accident</th>
</tr>
</thead>
<tbody>
<tr>
<td>2G/4G</td>
<td>2 g</td>
<td>No accident</td>
</tr>
<tr>
<td>2G/4G</td>
<td>4 g</td>
<td>Minor accident</td>
</tr>
<tr>
<td>On/off</td>
<td>15 g</td>
<td>Minor accident</td>
</tr>
<tr>
<td>On/off</td>
<td>30 g</td>
<td>Minor accident</td>
</tr>
<tr>
<td>On</td>
<td>52 g</td>
<td>Severe accident</td>
</tr>
<tr>
<td>Off</td>
<td>60 g</td>
<td>Severe accident</td>
</tr>
</tbody>
</table>

Evaluating the Model

Table 3 shows the result analysis of the proposed system. Based on Table 3, the accident severity was determined. The created AcciDet TracSys and AcciAddr TracSys have been put to the test in six scenarios involving Grav-force values. If the Grav-force is less than the threshold, irrespective of the network, the tilt sensor will not activate and no intimation of the accident is shared. On the other hand, in the 2G/3G service area, the tilt sensor will turn on if the Grav-force value overdoes the peak value. However, an SMS was used to send out the accident location and notification. In the meantime, if the Grav-force value in the 4G coverage area exceeds the peak value, the tilt sensor will activate and send the report of the accident site.

Results and Discussion

An accident is detected through Grav-forces and also through tilt and flame sensors. Figure 5a-b shows the tilt and flame detection which helps to understand the severity of an accident. Figure 5c shows that XYZ met with an accident and was notified about the accident occurrence to the nearest ambulance and was accepted by ambulance (ABC). Figure 5d shows the interface for showing the ambulance location and accident location. If the accident is minor and emergency assistance is not required. Figure 5e shows a push button that can be used to stop the auto system call for assistance.

(a)  
(b)  
(c)
Conclusion

To address the issue of the increasing proportion of fatalities owing to prolonged delays in responding to serious incidents, an internet of things-based accident detection, tracking, and addressing system, an alerting system involving telegram and SMS has been developed. AcciDet TracSys and AcciAddr TracSys can fill a gap found in a prior study where there was only accident detection but did not address the timely arrival of the ambulance and tracking it. Furthermore, the tested system's performance has been verified using a variety of Grav-forces and is capable of reducing the number of fatal incidents. In the future, this system can be enhanced by adding alert features for help services and building smart hospitals and smart ambulances that can follow the smart ambulances carrying patients and monitor them. Also, it can further be enhanced to understand and get the previous medical history of the patients so that the treatment can be planned well in advance.

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Author’s Contributions

Amreen Ayesha: Participated in all experiments, coordinated the data analysis, and contributed to the written of the manuscript.

Komalavalli Chakravarthi: Supervising and final drafted preparation.

Availability of Data and Materials

Real-time data is taken from the sensors for the study.

Competing Interests

“Not applicable”. We, as authors, have no conflicts of interest to declare that are relevant to the content of this research article. We also certify that they have no affiliations with or involvement in any organization or entity with any financial interest or non-financial interest in the subject matter or materials discussed in this manuscript. We, as authors, have no financial or proprietary interests in any material discussed in this research article.

Ethics

This article is original and contains unpublished material. The corresponding author confirms that all of the other authors have read and approved the manuscript and that no ethical issues are involved.
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