

Corrigendum: Inverse Kinematics of a Stewart Platform

¹Relly Victoria Virgil Petrescu, ²Raffaella Aversa, ²Antonio Apicella, ³Samuel Kozaitis, ⁴Taher Abu-Lebdeh and ¹Florian Ion Tiberiu Petrescu

¹*ARoTMM-IFTToMM, Bucharest Polytechnic University, Bucharest, (CE) Romania*

²*Department of Architecture and Industrial Design, Advanced Material Lab, Second University of Naples, 81031 Aversa (CE) Italy*

³*Florida Institute of Technology, USA*

⁴*North Carolina A and T State University, USA*

Correction to: Journal of Mechatronics and Robotics

<http://doi.org/10.3844/jmrsp.2018.45.59>, published online 10 March 2018; updated 29 April 2019

The original version of this Article contained Mr. MirMilad Mirsayar as a Co-Author. Mr. Mirsayar has not contributed to the preparation and publication of this manuscript.

These errors have now been corrected in the HTML and PDF versions of the Article. <http://doi.org/10.3844/jmrsp.2018.45.59>.